

ASPE 2020 Spring Topical Meeting: Design and Control of Precision Mechatronic Systems
Wednesday - Friday, May 6-8, 2020 (EDT)
Virtual Meeting: hosted via Zoom

Wednesday, May 6, 2020

8:00 AM - 8:30 AM	AM Tutorial Open for Connecting
8:30 AM - 12:30 PM	AM Tutorial <i>Advanced Feedforward and Iterative Learning Control for Precision Mechatronics</i> Dr. Tom Oomen (Eindhoven University of Technology)
12:30 PM - 1:30 PM	Break
1:00 PM - 1:30 PM	PM Tutorial Open for Connecting
1:30 PM - 5:30 PM	PM Tutorial <i>Introduction to Machine Learning and Reinforcement Learning for Precision Engineers</i> Dr. Amir Barati Farimani (Carnegie Mellon University)

Thursday, May 7, 2020

9:00 AM - 9:25 AM	Meeting Open for Connecting
9:25 AM - 9:30 AM	Opening Remarks
9:30 AM - 11:00 AM	Session I: Industry 4.0 and Learning Control <ul style="list-style-type: none"> • <i>How Learning Control Supports Industry 4.0 in Semiconductor Manufacturing</i> Gijs van der Veen • <i>Advanced Feedforward Control as a Service from the Cloud</i> Chinedum Okwudire • <i>Procedure Control of Nano Materials Design via Reinforcement Learning</i> Yuyang Wang • <i>Long-range Piezo-stepper Actuators: Towards Nanoscale Accuracy Through Commutation-angle Iterative Learning Control</i> Leontine Aarnoudse
11:00 AM - 11:30 AM	Keynote <i>Perspectives on Precision Mechatronics</i> Ton Peijnenburg (Eindhoven University of Technology)
11:30 AM - 12:45 PM	Session II: Advances in Motors <ul style="list-style-type: none"> • <i>Harness the Lag: Precision Positioning with Hysteresis Motors</i> Lei Zhou • <i>Design and Measurement of a 6-Phase Combined Winding Bearingless Synchronous Reluctance Slice Motor</i> Wolfgang Gruber • <i>Closed-loop Suspension and Rotation of a Spherical Permanent Magnetic Dipole Actuator</i> Tyler Hamer • <i>A Novel Position Sensing System for Bearingless Motors</i> Benjamin Weinreb
12:45 PM - 1:30 PM	Break (breakout rooms will remain open)
1:30 PM - 3:00 PM	Session III: Advances in Autotuning and Feedforward Control <ul style="list-style-type: none"> • <i>Auto-Tuning of Precision Servo Controllers Suffering from Large Mass Ratio Induced Vibrations</i> Alper Dumanli • <i>Combined Feedforward Tracking Control and Feedrate Optimization - with Application to a Precision XY Stage</i> Heejin Kim • <i>Feedforward Spectral Tuning and Using Iterative Learning Control For Automated Parameter Fitting</i> Leon Jabben • <i>Adaptive Feedforward Control of a Flexure Based Hexapod</i> Sil Spanjer

3:00 PM - 4:00 PM	Session IV: Advances in Mechatronic Design I <ul style="list-style-type: none"> • <i>Vacuum Compatible Contactless Active Magnetic Linear Bearings for High Cleanliness Robotic Applications</i> Rick Baade • <i>Variable Resolution Fused Filament Fabrication (FFF) Printing Using a Variable Orifice Extruder System</i> Osama Habbal • <i>Design and Control of a Thermal Actuation System</i> Chunjie Fan
4:00 PM - 5:00 PM	Online Socializing
Friday, May 8, 2020	
9:00 AM - 9:25 AM	Meeting Open for Connecting
9:25 AM - 9:30 AM	Opening Remarks
9:30 AM - 11:00 AM	Session V: Advances in Sensing and Feedback Control I <ul style="list-style-type: none"> • <i>Low-cost, High Dynamic Range Position Sensing Enabled by Oversampling and Averaging</i> Brij Bhushan • <i>Improved Current Control of Inverter Fed Two-phase Bipolar Stepper Motors Using Repetitive Control</i> Boaz Kramer • <i>Dynamics and Control of the PTB Nanometer Comparator</i> Paul Koechert • <i>Heuristically Optimized H-Infinity Synthesis for the Real-time Positioning of a Tip-based Measurement Device</i> Liam G. Connolly
11:00 AM - 11:30 AM	Keynote <i>Nanomanufacturing Enabled by Precision Systems, In-Situ Metrology and Real-Time Control</i> Prof. S.V. Sreenivasan (NASCENT Center, The University of Texas at Austin)
11:30 AM - 12:45 PM	Session VI: Advances in Sensing and Feedback Control II <ul style="list-style-type: none"> • <i>Model and Controller Design for High-speed Atomic Force Microscope Imaging and Autotuning</i> Fangzhou Xia • <i>Implementation of Length Control of an Optical Cavity Using Second-order Transverse Modes</i> Alvaro Fernandez-Galiana • <i>Active Optical Mode Matching for the Quantum Squeezing Cavities and Upcoming LIGO Upgrades</i> Fabrice Matichard • <i>Dynamic Characterization of Lapping Manipulator</i> Daegweon Koh
12:45 PM - 1:30 PM	Break (breakout rooms will remain open)
1:30 PM - 3:00 PM	Session VII: Modeling and Control of Precision Machines <ul style="list-style-type: none"> • <i>Reduced thermo-mechanical model of a rotary table of a 5-axis precision machine tool</i> Pablo Hernandez-Becerro • <i>Loop-shaping Controller Design in the Development of the High-Dynamic Double-Crystal Monochromator at Sirius Light Source</i> Ricardo Caliri • <i>Dynamic Error Budgeting in the Development of the High-Dynamic Double-Crystal Monochromator for Sirius Light Source</i> Renan Geraldes • <i>The FPGA Control Implementation of the High-Dynamic Double-Crystal Monochromator at Sirius Light Source</i> Marcelo Moraes

3:00 PM - 3:45 PM	Session VIII: Advances in Mechatronic Design II • <i>Delta Robot Combining Millimetre Travel With Nanometre Performance</i> Jon Kelly • <i>Thermally-Stable Precision Motion and Positioning Mechanism</i> Heebum Chun
3:45 PM - 4:15 PM	Keynote <i>Robots with Physical Intelligence</i> Prof. Sangbae Kim (Biomimetic Robotics Laboratory, Massachusetts Institute of Technology)
4:15 PM - 5:00 PM	Online Socializing